

$R_1 = 1 \Omega$

$N = 100$

$R_2 = 2 \Omega$

$U_{kA} = 12 \text{ V} \angle 180^\circ$

1) $V_{0(kA)} = \epsilon_0 - I_0 \cdot R_1$
 $12 = \epsilon_0 - \frac{\epsilon_0}{R_1 + R_2} \cdot R_1$

$\epsilon_0 = \dots \Rightarrow B = \dots$

2) $\frac{P_{max}}{P} = \frac{I_0^2 \cdot R_1}{I_{ev}^2 \cdot R_1}$

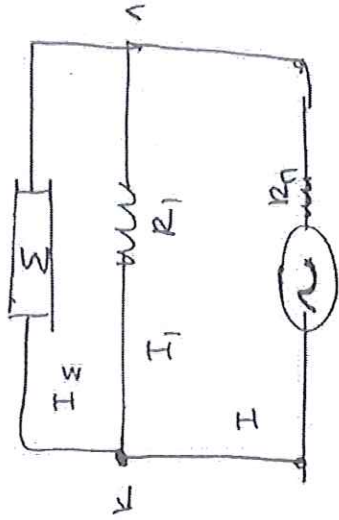
*3 επιλογές
1 η σωστή*

3) $Q = I_{ev}^2 R_{0\eta} (T)$

4) $\epsilon_{r\eta} = - \left(\frac{\Delta \phi}{\Delta t} \right) N = \epsilon_0 \omega \mu \angle 180^\circ + 81 \text{ V}$

$V_{kA} = 12 \text{ V} \angle 180^\circ = 6 \text{ V}$

ε)



$P_\Sigma = 300 \text{ W}$

$V_\Sigma = 10\sqrt{2} \text{ V}$

$P_\Sigma = V_\Sigma \cdot I_\Sigma \rightarrow I_\Sigma = \dots$

$R_\Sigma = \frac{V_\Sigma}{I_\Sigma} \rightarrow R_\Sigma = \dots$

$I_0 = \frac{\epsilon_0}{R_{0\eta}}$

$R_{0\eta} = R_{\eta 1} + R_{1, \Sigma}$

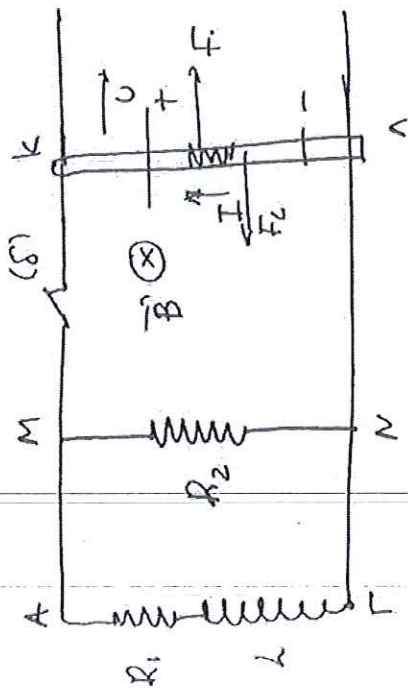
$V_{0(kA)} = I_0 \cdot R_{1, \Sigma}$

$V_\Sigma = V_{ev(kA)} = \frac{V_{0(kA)}}{\sqrt{2}} = \dots = 3\sqrt{2} \text{ V}$

ΑΡΑ ΔΕΝ ΛΕΙΤΟΥΡΓΕΙ ΚΑΝΟΝΙΚΑ

$P_\Sigma = \frac{V_{ev(kA)}^2}{R_\Sigma} = 27 \text{ W}$

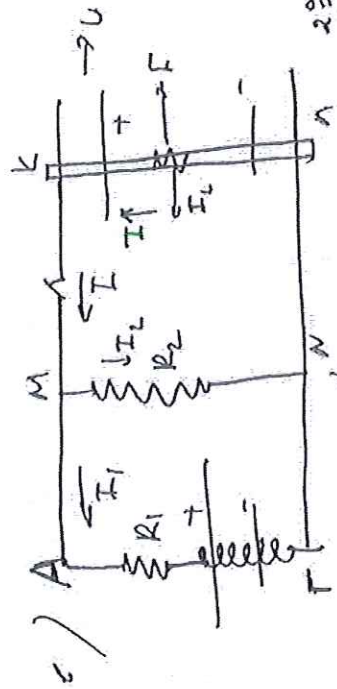
ASK. 34.



$l = 1 \text{ m}$
 $R_1 = 30$
 $l = 0,2 \text{ W}$
 $R_2 = 60$
 $m = 0,3 \text{ kg}$
 $R_{\text{ind}} = 2 \text{ O.}$
 $B = 1 \text{ T}$
 $F = 3 \text{ N}$

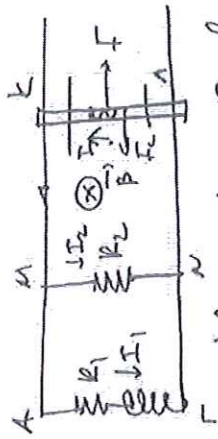
$\alpha) F = B \cdot I \cdot l$
 $I = \frac{B \cdot U \cdot l}{R_{1,2} + R_{\text{ind}}}$

• OTKO U → 67x10³ To analysis dynamic



$T_{\text{sw}} t = 0 \quad I_1 = 0$
 $\text{App } I = I_2 = \frac{B \cdot U \cdot l}{R_2 + R_{\text{ind}}}$

$\text{2. } \text{KizChof} \cdot (A \cdot K \cdot A \cdot T \cdot A)$
 $\text{Ked } |E_{\text{ind}}| = l \cdot \frac{\Delta I}{\Delta t}$



$\gamma) T_{\text{sw}} t_1$
 $I = \frac{B \cdot U \cdot l}{R_{1,2} + R_{1,2}}$

$V_{\text{AT}} = V_{\text{ch}} = B \cdot U \cdot l - I \cdot R_{\text{ind}}$

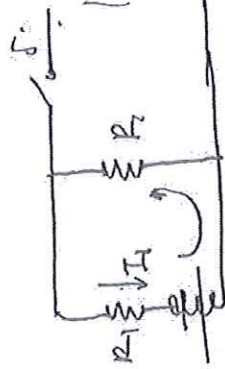
$l \cdot I_1 \cdot I_1 = \frac{V_{\text{AT}}}{R_1}$

$\phi = B \cdot \Sigma \text{Flux} \cdot A \quad (k = \mu_0 \cdot N \cdot A \cdot \frac{l}{l})$
 $B_{\Sigma \text{Flux}} = \mu_0 \cdot I_1 \cdot \frac{N \cdot A}{l}$

$\frac{l}{B} = \frac{N \cdot A}{I_1}$
 $B \cdot A = \frac{l \cdot I_1}{N}$

$U_L = \frac{1}{2} L I_1^2$

$\delta) Q = I_2 \cdot \Delta t$
 $Q_2 = I_2^2 R_2 \cdot \Delta t \quad (I_2 = \frac{V_{\text{ch}}}{R_2})$

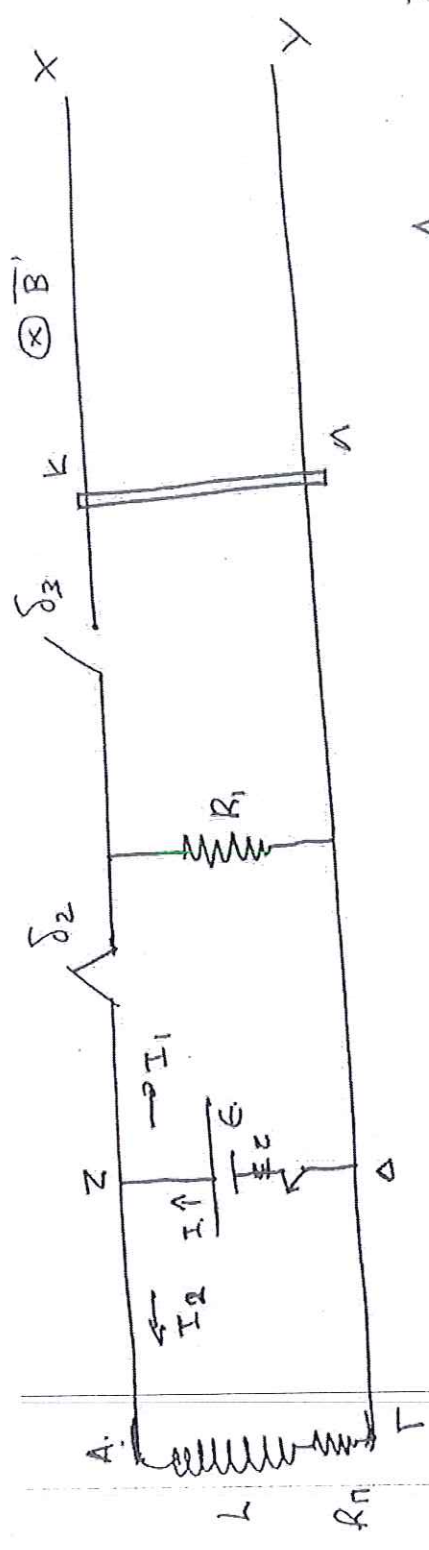


$\frac{\Delta I}{\Delta t} = \dots$

$Q_{\text{on}} = \frac{1}{2} L I_1^2$

$Q_{\text{on}} = Q_{R_1} + Q_{R_2}$

$\frac{Q_{R_1}}{Q_{R_2}} = \frac{R_1}{R_2}$



A) orda ra esay dda gind, garsid to dario gup woei vepeta w) dardidra

$l = 2m$

$l = 0,4 H$

$R_{p1} = 15 \Omega$

$N = 1000$

$E = 32 V$

$Z = 2 \Omega$

$R_1 = 10 \Omega$

$m = 164$

$R_{kn} = 10 \Omega$

$B = 1 T$

$I = \frac{E}{R_{p1} + Z}$

$V_{z\Delta} = E - I \cdot Z$

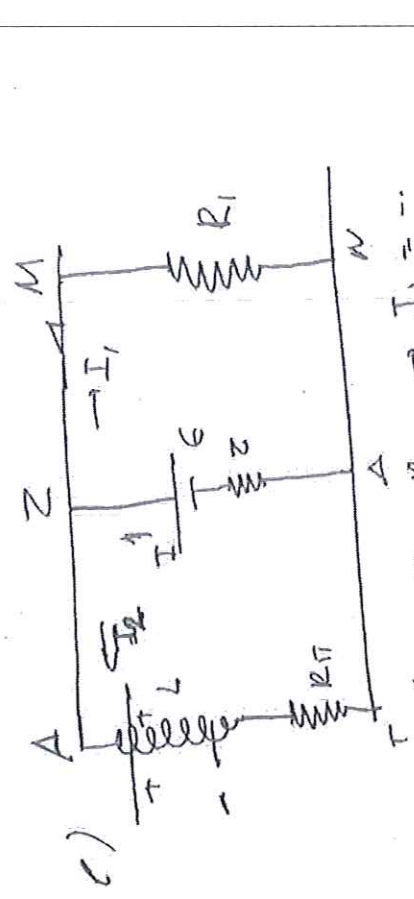
$V_{z\Delta} = V_{AT} = I_2 \cdot R_{kn} \rightarrow I_2 = \dots$

$B_{sen} = \mu_0 I_2 \frac{N}{l}$

$\phi = B \cdot A = \frac{\mu_0 I_2 N \cdot A}{l}$

$\frac{\phi}{l} = \mu_0 \frac{N^2 \cdot A}{l}$

$\Rightarrow \dots \phi = \dots$



$V_{z\Delta} = I_1 \cdot R_{p1} \rightarrow I_1 = \dots$

$V_{z\Delta} = V_{z\Delta} = E - I \cdot Z \Rightarrow I = \dots$

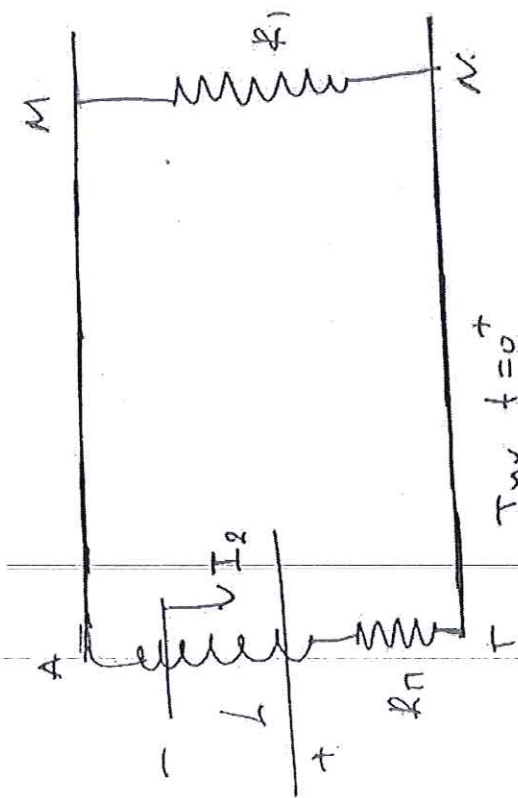
$I = I_1 + I_2 \rightarrow I_2 = \dots$

\dots

\dots

$+ I_1 R_{p1} - l \frac{dI}{dt} - I_2 R_{kn} = 0$

ΑΣΚ 37
Συνιστά

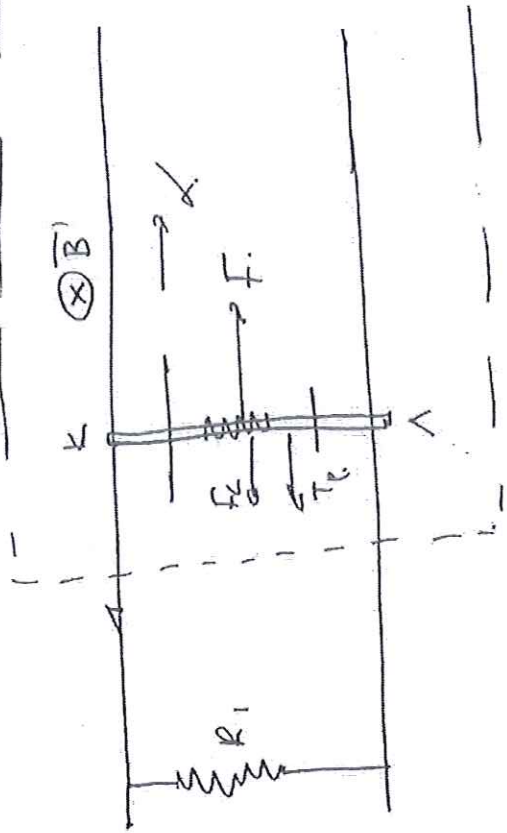


$T_{\text{av}} t = 0^+$

$\oint \mathcal{E} dt = I_2 \cdot (R_{\pi} + R_1) = L \cdot \frac{\Delta I_2}{\Delta t} = \dots$

($I_2 \rightarrow 70$ ΓΑΛΙΛΕΟ ΡΕΦ)
 πρω κύβου ρεφ
 670 κ. Εργασία

$Q = \frac{1}{2} L I_2^2 = \dots$

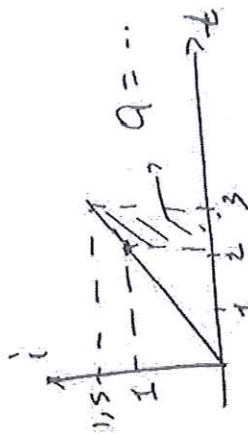


$P_F = F \cdot U$

$U = \mathcal{E} \cdot t$

$\Sigma F = m \cdot a \Rightarrow F - B i l - T = m \cdot a$

$I = \frac{B U l}{R_1 + R_{\text{rod}}} = \frac{1 \cdot U \cdot 2}{10 + 10} = 0,5 \cdot t$



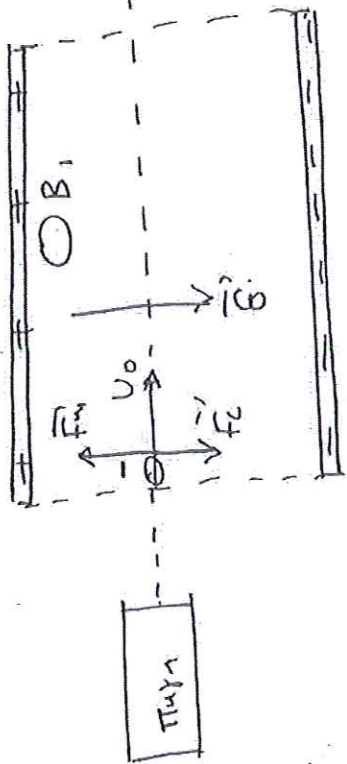
Θ. Μ. Κ 2 → 3 sec Q_{total}

$\frac{1}{2} m U_3^2 - \frac{1}{2} m U_2^2 = W_F - W_{F1} - W_T$

$U_3 = \mathcal{E} \cdot t_3 \quad W_T = T \cdot \Delta x_{2,3} = T \cdot \left(\frac{1}{2} \times t_3^2 - \frac{1}{2} \times t_2^2 \right)$

$U_2 = \mathcal{E} t_2$

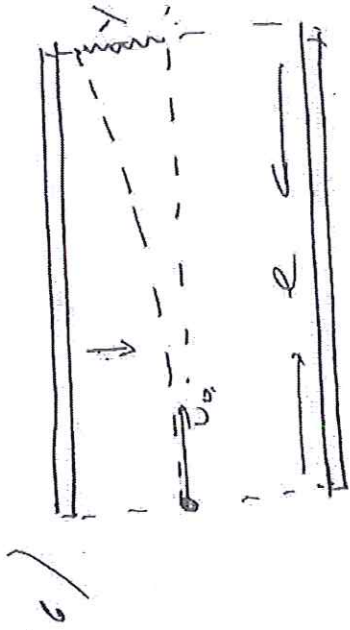
$l = 1,25 \text{ cm}$
 $\epsilon = 3,5 \cdot 10^3 \text{ V/m}$
 $U_0 = 1,25 \cdot 10^4 \text{ V/m}$
 $B_2 = 0,1 \text{ T}$
 $d = 5 \text{ mm}$
 $\gamma = 5 \text{ mm}$



a) \vec{B}_1 \otimes Σ \perp \vec{v} \perp \vec{v} \perp \vec{v}

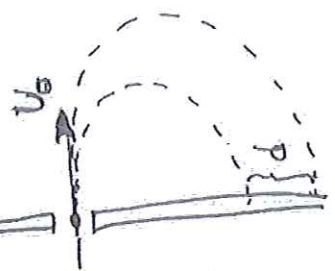
$\Sigma F = 0 \Rightarrow \epsilon \cdot l \cdot q = B_1 U_0 l q$

$B_1 = \dots$



$e = U_0 \cdot t$
 $\gamma = \frac{1}{2} a \cdot t^2$
 $\alpha = \frac{\epsilon \cdot l \cdot q}{m_1} \rightarrow m_1 = \dots$

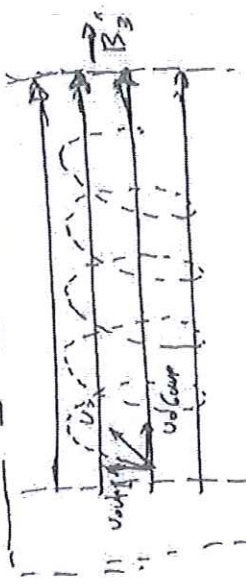
$\otimes \vec{B}_2$



$d = 2 R_2 - 2 R_1$
 $d = 2 \cdot \frac{m_2 U_0}{B_2 l q} - 2 \cdot \frac{m_1 U_0}{B_2 l q}$

$m_2 = \dots$

$\delta) \Delta t = \left| \frac{T_2}{2} - \frac{T_1}{2} \right|$



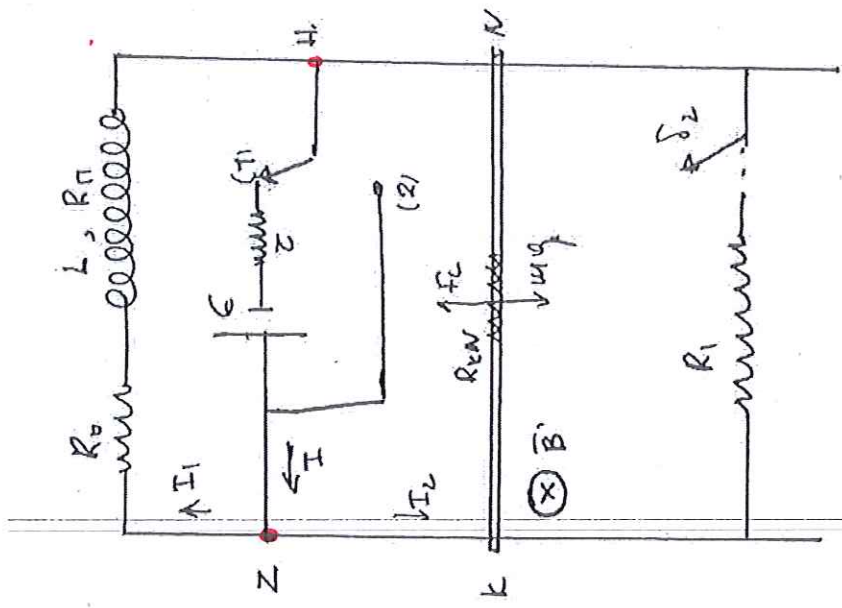
$T = \frac{2 \pi m_1}{B_3 l q}$

$l_{\text{path}} = U_0 \text{ Gear } T$

$l = N \cdot l_{\text{path}}$

grupp

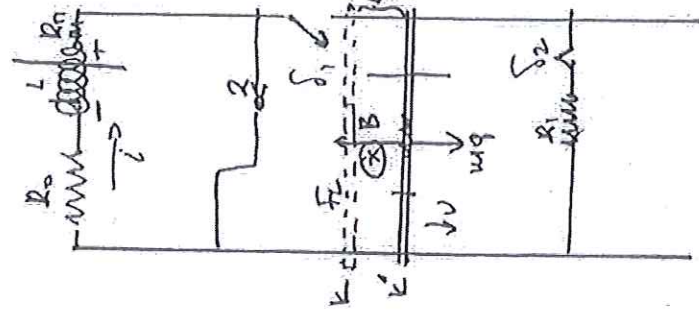
ASK. 43



$R_0 = 4 \Omega$
 $R_1 = 1 \Omega$
 $l = 0,5 \text{ m}$
 $n = 1000 \text{ turns/m}$
 $\mathcal{E} = 35 \text{ V}$
 $r = 2,5 \Omega$
 $m = 0,5 \text{ kg}$
 $R_{\text{ext}} = 3 \Omega, B = 1 \text{ T}$

$\Sigma F = 0 \Rightarrow$
 $F_2 = m \cdot g \Rightarrow$
 $B I_2 l = m \cdot g$
 $V_{KN} = I_2 R_{\text{ext}}$
 $V_{KN} = V_{ZU} = \mathcal{E} - I \cdot r$
 $I = I_1 + I_2 \rightarrow I_1 = \dots$

τ_2



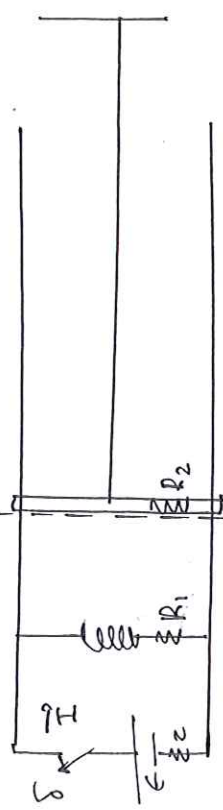
$P_{R_0} = I^2 \cdot R_0 \rightarrow L = \dots$
 $Q = \frac{1}{2} L I_1^2 - \frac{1}{2} L I_2^2$
 $\mathcal{E}_{\text{ind}} = i (R_0 + R_n) \Rightarrow L \frac{\Delta i}{\Delta t} = i (R_0 + R_n)$

Kiri Tur t_1 $\Sigma F_{\text{ext}} = 0 \Rightarrow m g = F_L \Rightarrow$
 $m g = B \cdot \frac{B U l}{R_1 + R_{\text{ext}}} \cdot l \rightarrow U = \dots$
 - Gerak Kiri t_1 $\Delta \Phi_{\text{ind}} = \frac{1}{2} g t_1^2$
 $\Delta \Phi = B \cdot \Delta A = B \cdot l \cdot \Delta x$
 $g \rightarrow t_2 = g t_1 \rightarrow t_2 = l \cdot \Delta x = \frac{B U l}{R_1 + R_{\text{ext}}} \cdot (t_1)$

$t = 0 \rightarrow t_2$
 $\Delta y = \frac{1}{2} g t_1^2 + U \cdot \Delta t$
 $\frac{\Delta \Phi}{\Delta U} = \frac{\frac{1}{2} m U^2 - 0}{-m g (\Delta y)}$

$V_{ZH} = I_1 (R_0 + R_n)$
 $R_n = \dots$

ΑΣΕ 44



$\ell = 1 \text{ m}$

$\epsilon = 3,6 \text{ V}$

$\zeta = 0,6 \Omega$

$\lambda = 0,8 \text{ H}$

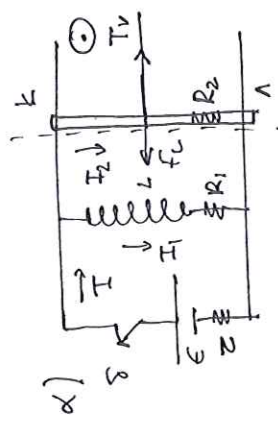
$R_1 = 0,4 \Omega$

$M = 1,25 \text{ kg}$

$\ell = 1 \text{ m}$

$R_2 = 1,2 \Omega$

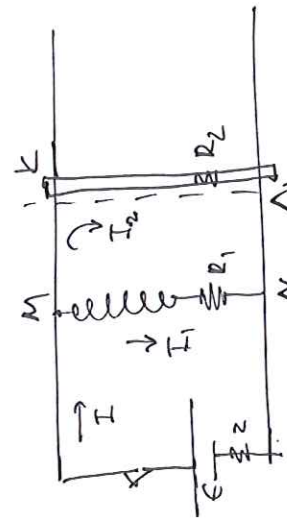
$B = 1 \text{ T}$



ΑΞΙΩΣ ΜΕΤΑ.

$I_1 = 0, I = I_2 = \frac{\epsilon}{R_2 + \zeta} = \frac{3,6}{1,8} = 2 \text{ A}$

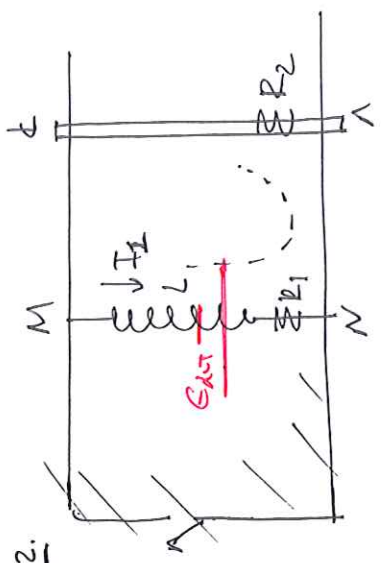
$\bullet \Sigma F = 0 \Rightarrow T_V = B I_2 \ell = 2 \text{ N}$



ΟΤΑΝ ΤΑ ΡΕΥΜΑΤΑ ΕΙΝΑΙ ΣΤΑΘΕΡΑ ΤΟ ΠΗΜΟ ΣΥΜΠΕΡΙΦΕΡΕΤΑΙ ΟΣ ΑΓΩΓΟΣ

$I = \frac{\epsilon}{R_{\text{ON}}} = \frac{\epsilon}{R_1 + \zeta + R_2} = \frac{3,6}{0,9} = 4 \text{ A}$

Α2.



ΑΞΙΩΣ ΜΕΤΑ ΤΟ ΑΝΟΙΓΜΑ ΤΟΥ ΔΙΑΚΛΟΠΗ (δ)

$I_{\text{ΠΗΜΟ}} = I_2 = 2 \text{ A}$
ΚΑΙ ΜΕΙΩΝΕΤΑΙ ΑΡΔ ΑΝΑΠΤΥΣΣΕΤΑΙ ΕΑΥΤ ΤΙΑ ΝΑ ΤΟ ΣΥΝΤΗΡΗΣΕΙ

$P_{R_2} = I^2 \cdot R_2$

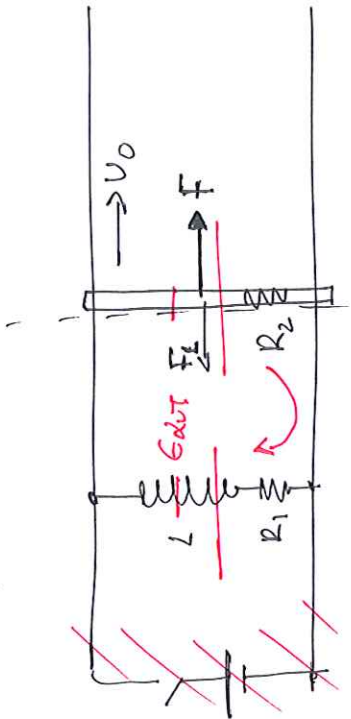
$I = \frac{|\epsilon_{\text{EXT}}|}{R_1 + R_2} \Rightarrow \dots \left| \frac{\Delta \ell'}{\Delta t} \right| = \dots$

ΚΑΙ $\frac{\Delta U_L}{\Delta t} = \epsilon_{\text{EXT}} \cdot \dot{I}$

$\mathcal{O}_{R_{\text{ON}}} = U_L = \frac{1}{2} L I_1^2$

$V_{\text{KN}} = V_{\text{ΠΟΛ}} = \epsilon - I \cdot \zeta = 1,2 \text{ V}$
 $I_2 R_2 = 1,2 \text{ V} \Rightarrow I_2 = 1 \text{ A}$
 $\Sigma F = 0 \Rightarrow T_V = B I_2 \ell = 1 \text{ N}$

A 2k 44
GUVLEX 2k



$$i = 0,5 \text{ A} + 1 \Rightarrow \frac{\Delta i}{\Delta t} = 0,5 \frac{\text{A}}{\text{s}}$$

$$i = \frac{\epsilon_{\text{eff}} - |\epsilon_{\text{ind}}|}{R_{\text{tot}}} \Rightarrow$$

$$0,5 \text{ A} + 1 = \frac{BUL - |\epsilon_{\text{ind}}|}{R_{\text{tot}}}$$

$$0,5 \text{ A} + 1 = \frac{U - 0,8 \cdot 0,5}{1,6}$$

$$0,8 \text{ A} + 1,6 = U - 0,4 \Rightarrow$$

$$U = 0,8 \text{ A} + 2 \quad \left. \begin{array}{l} U_0 = 2 \text{ m/s} \\ \alpha = 0,8 \text{ m/s}^2 \end{array} \right\}$$

für T_{rot} folgen $U = U_0 + \alpha \cdot t$

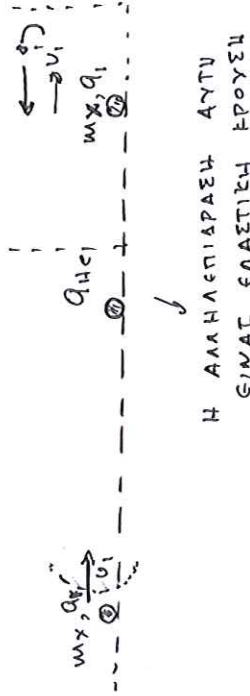
$$P_F = F \cdot U \quad (1)$$

$t = 1 \text{ sec}$

$$\cdot \Sigma F = W \cdot \alpha \Rightarrow F - B i \cdot l = W \cdot \alpha$$

$$\Rightarrow F = B i \cdot l + W \cdot \alpha = \frac{1,5 + 1,25 \cdot 0,8}{i = 0,5 \cdot (1) + 1 = 1,5}$$

$$(1) P_F = \dots = 7 \frac{\text{J}}{\text{s}}$$



Δ1 ΣΤΟΝ ΧΩΡΟ ΤΩΝ ΑΥΟ ΠΕΔΙΩΝ

$$\sum F = 0 \Rightarrow \epsilon \cdot q_{He} = B_1 \cdot U_{He} \cdot q_{He} \Rightarrow B_1 = \dots$$

$$\frac{1}{2} m_1 U_1'^2 = \frac{36}{100} \frac{1}{2} m U_1^2 \Rightarrow U_1' = \pm \frac{6}{10} U_1$$

$$(m_1 < m_2 \Rightarrow U_1' = -\frac{6}{10} U_1)$$

$$\text{και } U_1' = \frac{m_1 - m_2}{m_1 + m_2} U_1 \Rightarrow -\frac{6}{10} U_1 = \frac{m_1 - m_2}{m_1 + m_2} U_1$$

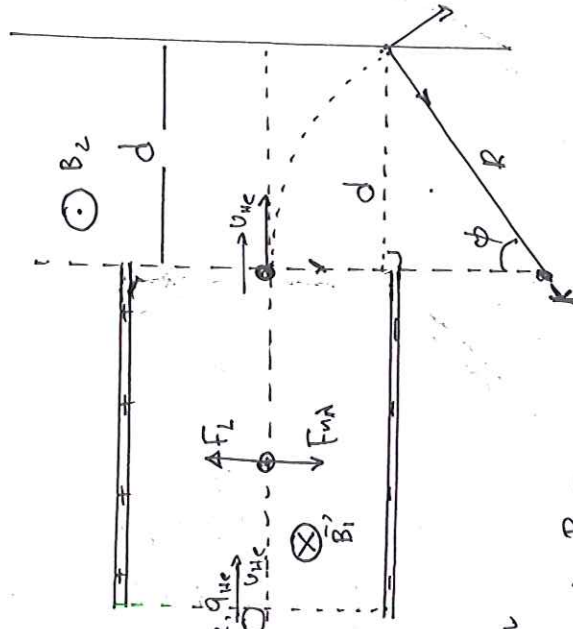
$$\Rightarrow m_1 = \frac{1}{4} m_2 = \frac{1}{4} \cdot 4 \text{ mp} \Rightarrow m_1 = \underline{\underline{1 \text{ mp}}}$$

ΑΡΑ ΤΟ ΣΕΜΑΤΙΔΙΟ (1) ΕΙΝΑΙ ΠΡΩΤΟΝΙΟ

$$m_1 = 1 \text{ mp}$$

$$q_1 = 9 \text{ p}$$

Α.Δ.Ο. ; $m_1 U_1' = m_1 U_1 + m_{He} U_{He}$
 $\text{μπ } U_1 = \text{μπ} \left(-\frac{6}{10} U_1 \right) + 4 \text{ μπ} \cdot 2 \cdot 10^4 \Rightarrow U_1 = \dots$

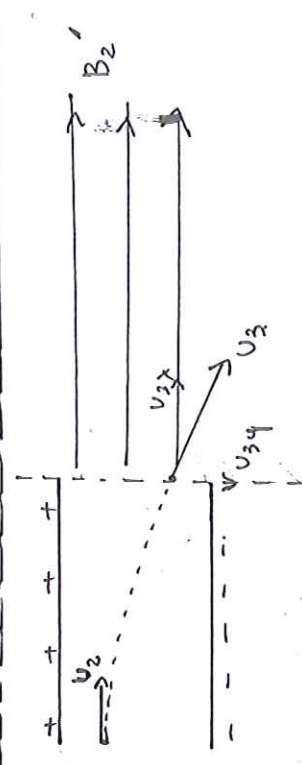


$$R = \frac{m_{He} \cdot U_{He}}{B_2 \cdot q_{He}} = \frac{4 \cdot \text{μπ} \cdot U_2}{B_2 \cdot 2 \cdot 9 \text{ p}}$$

$$\text{μπ } \phi = \frac{d}{R} = \dots$$

$$\hat{\phi} = \omega \cdot \Delta t = \frac{B_2 \cdot q_2}{m_2} \cdot (\Delta t)$$

ΤΙΣ ΝΑ ΣΥΝ ΕΣΕΡΧΕΤΑΙ ΟΡΙΣΜΟΣ
 ΠΡΩΤΟΝ. $R = d \Rightarrow \frac{m_2 U_2}{B_2 \cdot q_2} = d$

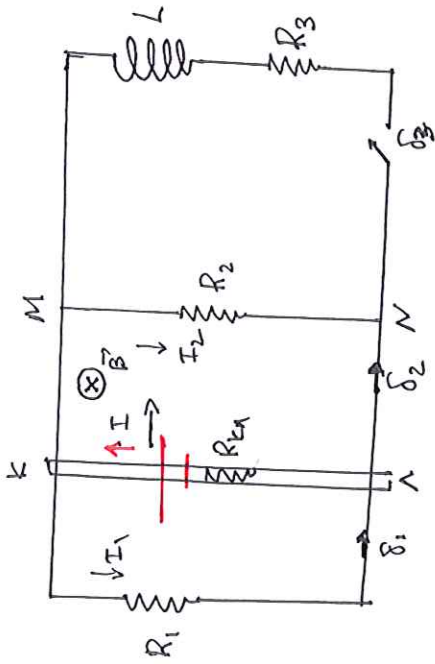


ΣΤΟ ΗΛ. ΠΕΔΙΟ $U_3 = \sqrt{U_{3x}^2 + U_{3y}^2} = \dots$

$$l = U_2 \cdot \Delta t$$

$$U_{3y} = \alpha \cdot \Delta t$$

$$\alpha = \frac{\epsilon \cdot q_2}{m_2}$$



$R_1 = 6 \Omega$

$L = 0,2 \text{ H} \quad \alpha) \quad I = \frac{\epsilon_{\text{eff}}}{R_{\text{ou}}} = \frac{4t}{4} = 1 \cdot t$

$R_3 = 6 \Omega$

$R_2 = 3 \Omega$

$m = 0,5 \text{ kg}$

$l = 1 \text{ m}$

$R_{k\lambda} = 2 \Omega$

$\alpha = 4 \text{ m/s}^2$

$B = 1 \text{ T}$

$R_{\text{ou}} = \frac{R_1 \cdot R_2}{R_1 + R_2} + R_{k\lambda}$

$\epsilon_{\text{eff}} = B U l = B(\alpha \cdot t) l$

$V_{k\lambda} = + (\epsilon_{\text{eff}} - I \cdot R_{k\lambda})$

$V_{k\lambda} = I \cdot R_{1,2} = 2t$

$t = 2 \text{ sec} \rightarrow V_{k\lambda} = 4 \text{ V}$

$\epsilon) \quad I_1 = \frac{V_{k\lambda}}{R_1} = \frac{4 \text{ V}}{6 \Omega} = \frac{2}{3} \text{ A}$

$P_{R_1} = I_1^2 \cdot R_1 = \frac{8}{3} \text{ W}$

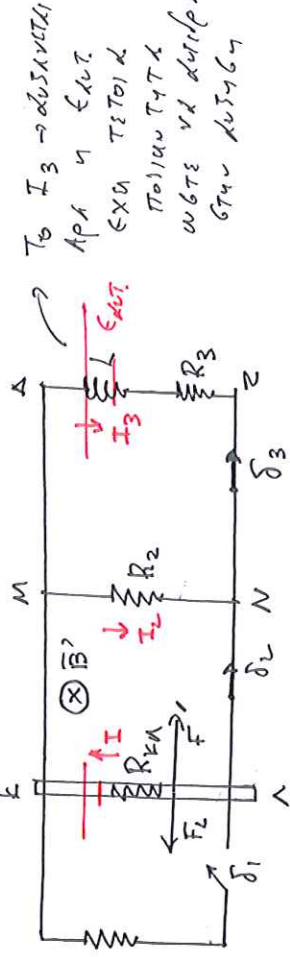
$\cdot t = 3 \text{ sec}$

$\Sigma F = m \cdot \alpha \Rightarrow F - B I l = m \cdot \alpha \Rightarrow$

$\Rightarrow F = B I_{\text{eff}} \cdot l + m \cdot \alpha = 5 \cdot N$

$U \rightarrow U_{\text{op}} \text{ O T A N } \Sigma F_{k\lambda} = 0 \Rightarrow P$

$F = B \frac{B U l}{R_{\text{ou}}} \cdot l \Rightarrow U_{\text{op}} = 20 \text{ m/s}$



$T_0 \quad I_3 \rightarrow \alpha \delta_3 \lambda \nu \epsilon \lambda \lambda$
 $\text{ΑΡΧΗ η ΕΛΥΤ. ΕΞΗ ΤΕΤΟΙΔ ΠΟΛΙΩΝ ΤΥΤΔ ΜΕΤΕ VΔ ΔΥΠΛΟΔ ΕΤΥΔ ΔΥΤΥΓΔ}$

ΑΡΙΘΜΟΣ ΜΕΤΑ

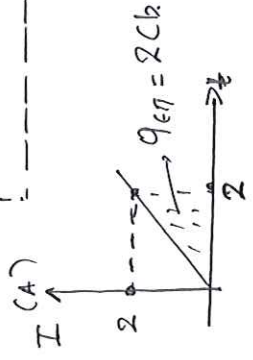
$I = I_2 = \frac{\epsilon_{\text{eff}}}{R_{\text{ext}} R_2} = \frac{20}{5} \quad A = 4 \text{ A}$

• ΠΑ ΤΟΝ $\frac{\Delta l}{\Delta t} \rightarrow \alpha \delta^2 \text{ ΚΑΝΟΝΑ ΝΕΥΤΟΝ}$
 (ΝΜ Δ Ζ Ν)

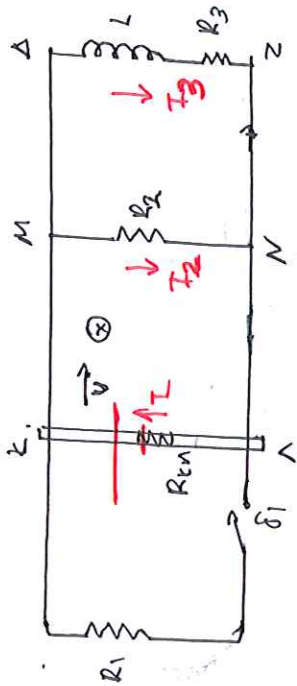
$+ I_2 R_2 - \epsilon_{\text{eff}} - I_3 R_3 = 0$

$\Rightarrow l \cdot \frac{\Delta l}{\Delta t} = I_2 R_2 \Rightarrow$

$\frac{\Delta l}{\Delta t} = 60 \frac{\text{A}}{\text{s}}$



ΑΣΚ 48 (ΣΥΝΕΧΕΙΑ)



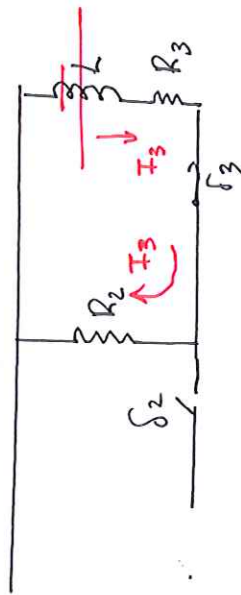
→ ΟΤΑΝ ΤΑ ΡΕΣΜΑΤΑ ΕΙΝΑΙ ΣΤΑΘΕΡΑ.

$$I = \frac{\mathcal{E}_{\text{eq}}}{R_{\text{eq}}} = \frac{20}{4} = 5 \text{ A.}$$

$$I_3 = \frac{V_{\Delta Z}}{R_3} = \frac{10 \text{ V}}{6 \Omega} = \frac{5}{3} \text{ A}$$

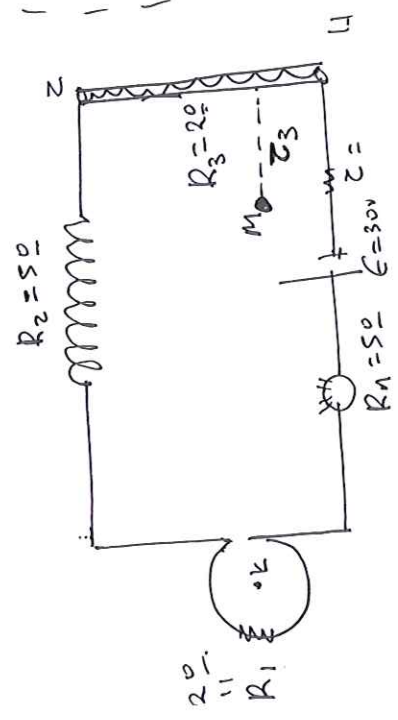
$$I_2 = \frac{V_{\text{MN}} = (V_{\text{eq}})}{R_2} = \frac{10 \text{ V}}{3 \Omega} = \frac{10}{3} \text{ A}$$

ΑΝΟΙΓΟΥΜΕ ΤΟΝ δ_2
ΑΚΡΙΒΟΣ ΜΕΤΑ



$$Q = U_2 = \frac{1}{2} L \cdot I_3^2 = \frac{5}{18} \text{ J.}$$

ΑΣΚ ΣΙ

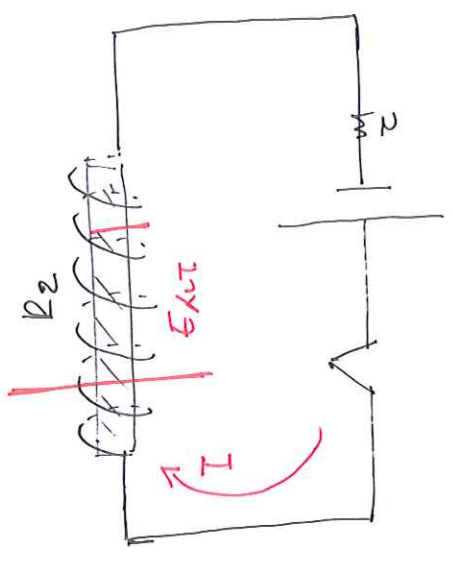


α) $I = \frac{\epsilon}{R_{\text{ολ}}}$ } $\Rightarrow r =$
 $I = I_1 = 2A$

β) $B_L = \frac{\mu_0 I}{2r_1}$
 $B_\Sigma = \mu_0 I \left(\frac{N_2}{l}\right)$

$B_M = \frac{\mu_0 I}{2\pi r_3}$

ΛΑΜΠΤΗΡΑΣ
 • $P_A = 20W$
 • $V_A = 10V$
 $P_A = V_A \cdot I_A \Rightarrow I_A = 2A$
 $R_A = \frac{V_A}{I_A} = 5\Omega$



$l' = \mu_0 L$
 δ) $I_{\text{τενιό}} = \frac{\epsilon}{R_2 + r}$

ΚΑΘΕ ΣΤΙΓΜΗ Ι ΣΧΥΕΙ
 ΣΜΕΥΡΙ ΜΑ ΤΙΜΕΙ Ι ΤΕΝΙΟ

• $l = \frac{\epsilon - l \cdot \frac{\Delta l}{\Delta t}}{R_{\text{ολ}}}$

γ) $l = \frac{\mu_0 N_2^2 (\pi r_2^2)}{l}$
 $U_L = \frac{1}{2} L \cdot I^2$

AΣK 54

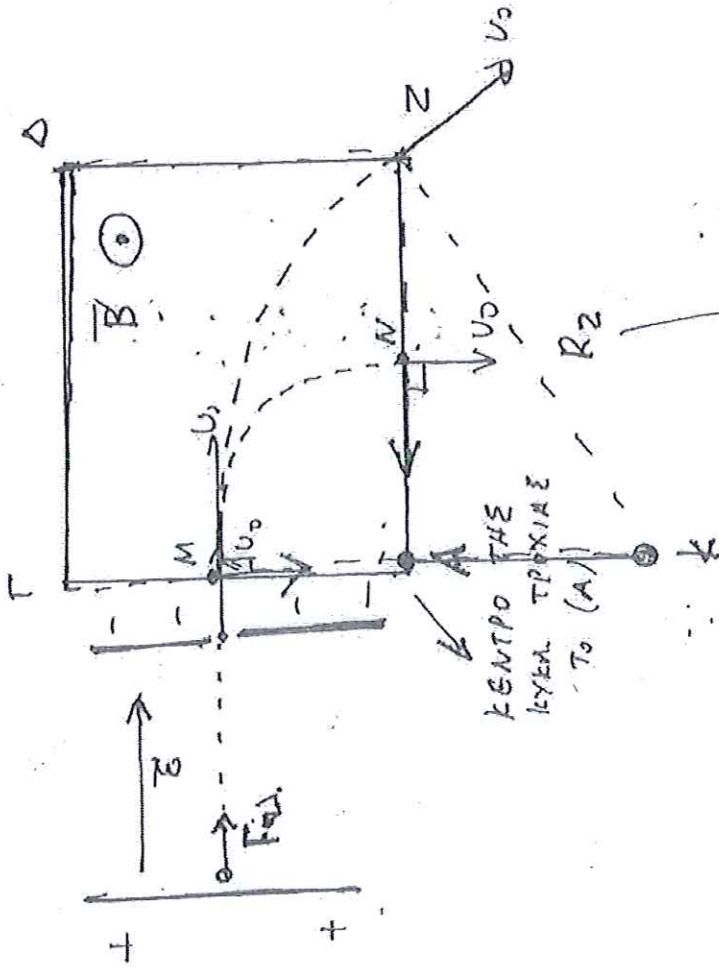
$$\frac{1}{2} m U_0^2 = v \cdot q$$

• οτιδη εγωνα κωο το (N)

$$R_1 = (AM) = (AN) \cdot 2cm$$

$$R_1 = \frac{m \cdot U_0}{B \cdot q}$$

$$B = \dots$$



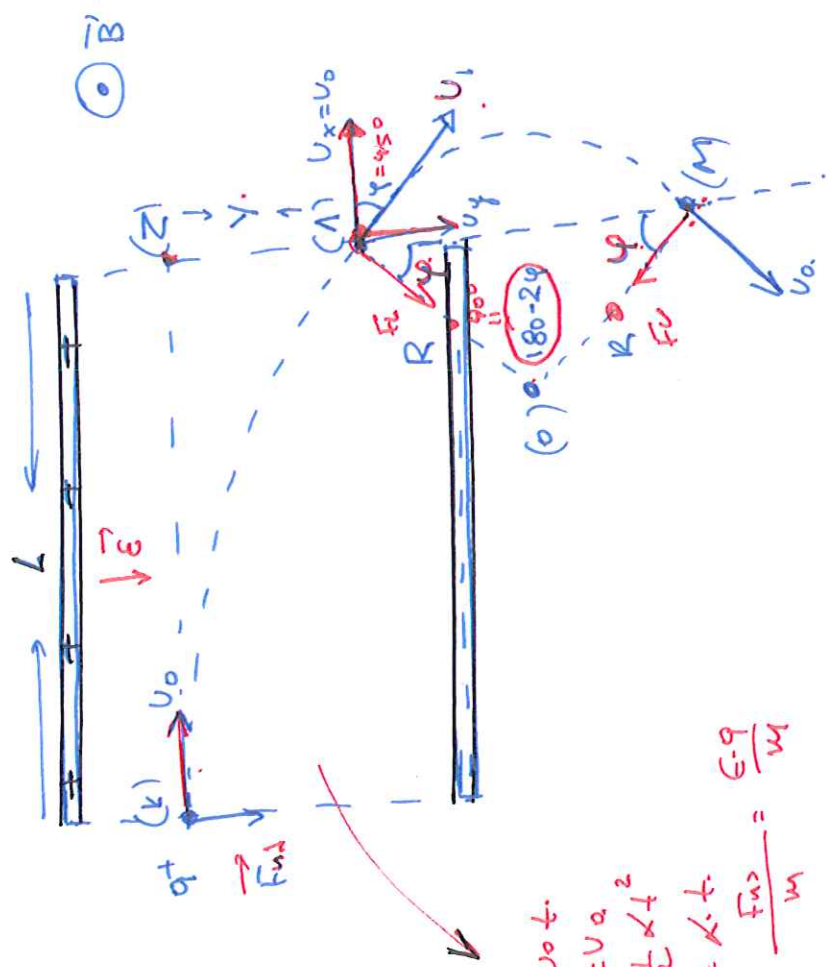
$$A \omega_0 \rightarrow R_2 = \dots$$

$$B_2 = \dots$$

$$(E) \cdot \mu p \epsilon \omega \epsilon \mu \Delta F = 0 \Rightarrow \underline{F_{L2} = F_L}$$

$m, g, v_0, \epsilon, L, B$

Azk 55



$$\begin{aligned}
 x &= v_0 t \\
 v_x &= v_0 \\
 y &= \frac{1}{2} \alpha t^2 \\
 v_y &= \alpha \cdot t \\
 \alpha &= \frac{F_{\text{net}}}{m} = \frac{\epsilon \cdot g}{m}
 \end{aligned}$$

$$v_1 = \sqrt{v_0^2 + (\alpha t)^2} = \dots$$

$$\alpha = \frac{\epsilon \cdot g}{m} \quad t = \frac{L}{v_0}$$

$$\epsilon \cdot y = \frac{v_y}{v_0} \Rightarrow \gamma = \dots = 45^\circ$$

$$R = \frac{m \cdot v_1}{B \cdot g}$$

$$\gamma) (ZM) = (Z\Delta) + (\Delta M)$$

$$(Z\Delta) = \gamma = \frac{1}{2} \alpha t^2$$

$$(\Delta M) \Rightarrow \text{Anso to } T_1, \text{ juw } v_0 \quad (0 \Delta M)$$

$$(\Delta M)^2 = R^2 + R^2 - 2 R \cdot R \cos(180 - 2\gamma)$$

$$t_{\text{on}} = t_{k\Delta} + t_{\Delta M}$$

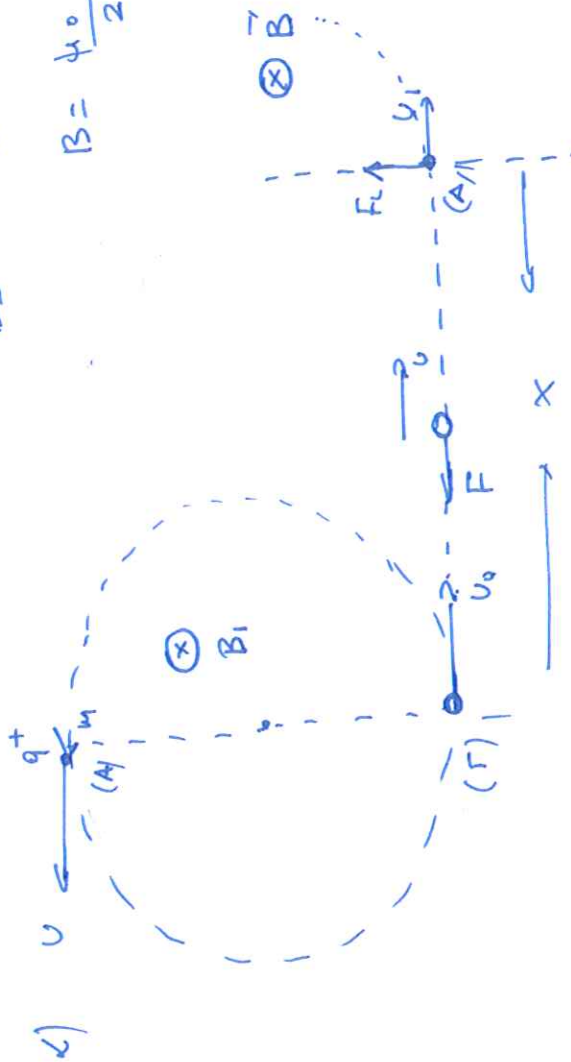
$\frac{L}{v_0}$ $\frac{L}{v_0}$

$\frac{90^\circ}{180 - 2\gamma}$

$$T = \frac{2\pi R}{U}$$

$$i = \frac{\Delta q}{\Delta t} = \frac{q}{T}$$

$$B = \mu_0 \frac{I}{2R} = \dots$$



$$R = \frac{m \cdot U_1}{B \cdot q}$$

$$T = \frac{2\pi m}{B \cdot q} \rightarrow \text{κεντροειδής και ακτινωτός του } \vec{B}$$

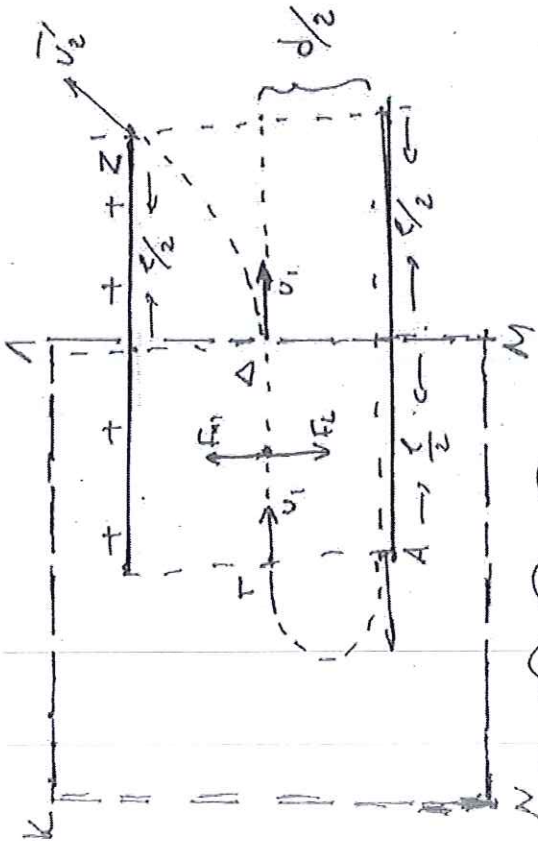
$$\Sigma F = 0 \Rightarrow \epsilon \cdot q = B \cdot U_1 \cdot q$$

$\Gamma \rightarrow \Delta$ Το συμπέριο είναι κυκλικό και κινείται

$$U_1 = v_0 - \frac{1}{2} \frac{F}{m} \Delta t$$

$$x = v_0 t - \frac{1}{2} \frac{F}{m} \Delta t^2$$

$$\frac{1}{2} m U_1^2 - \frac{1}{2} m v_0^2 = -F \cdot x$$



α) $A_{\omega 0} \tau_{xy} \tau_{yx} \Delta z \rightarrow (q)$

β) $U_0 = U_1$

$R = \frac{M U_0}{B \cdot q}$

γ) $\Sigma F = 0 \rightarrow E \cdot q = B \cdot U_1 \cdot q$

ε) $\Delta t = \frac{T}{2}$

ζ) $\Delta t_{r \rightarrow 2} = \Delta t_{r \rightarrow 1} + \Delta t_{\Delta \rightarrow 2}$

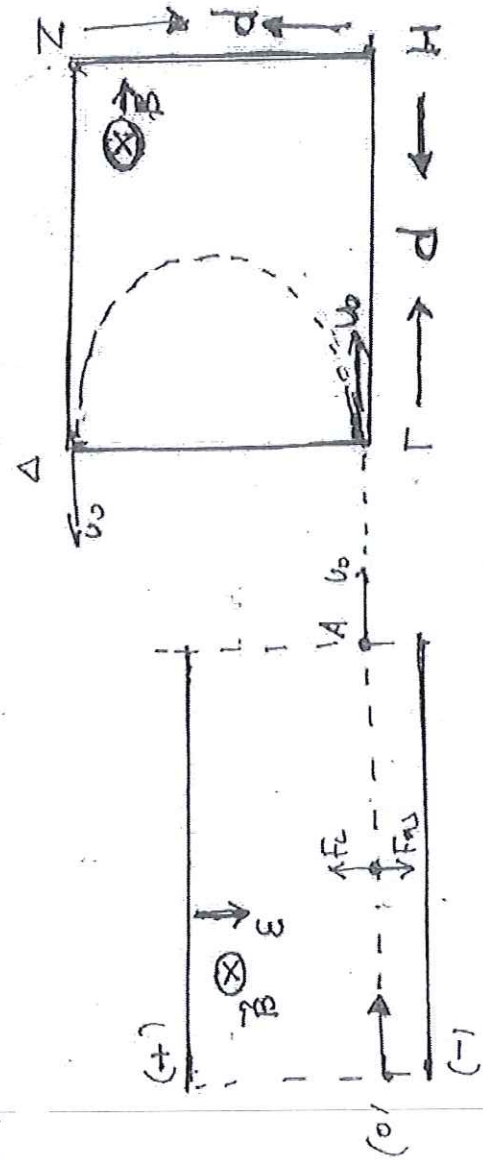
$\Delta t_{r \rightarrow \Delta} = \frac{l/2}{U}$

* $\frac{d}{2} = 2R \Rightarrow d = \dots$

$\Sigma \tau_{xy} \Delta z$ (kinematic)

$\frac{l}{2} = U \cdot \Delta t_{\sigma} \Rightarrow l = \dots$

$\frac{d}{2} = \frac{1}{2} \alpha \cdot \Delta t^2 \rightarrow \Delta t = \dots$



ΜΟΝΟΡΕΘΕΝ ΔΕΙΤΩ ΙΟΝΤΑ
 $q = +e = +1,6 \cdot 10^{-19} \text{ C}$

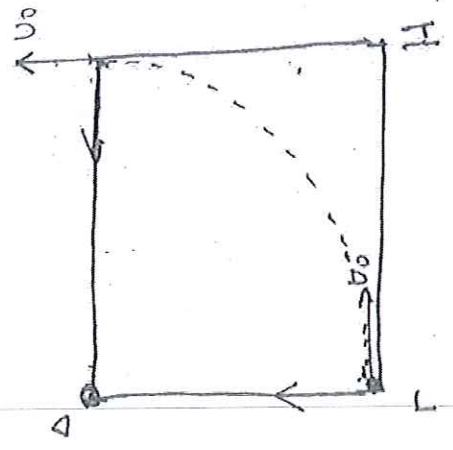
α) Στο επίπεδο ταχύτητας $\Sigma F = 0 \Rightarrow \epsilon \cdot \vec{v} = B v_0 \cdot \vec{q}$

β) $R = \frac{d}{2} \Rightarrow \frac{m v_0}{B' q} = \frac{d}{2} \rightarrow m = \dots$

$\Delta t = \frac{\tau}{2}$

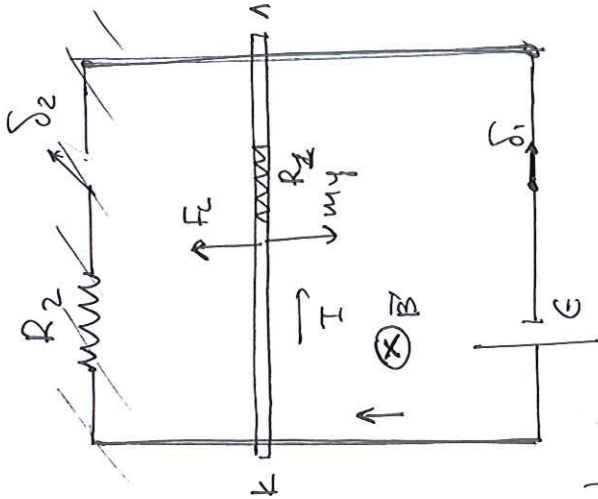
γ) $\Delta K = 0, \Delta P_{\Gamma, \Delta} = \vec{P}_{\Delta} - \vec{P}_{\Gamma} = P - (-P)$

δ) Το κέντρο του κύκλου τωπά είναι το (Α)
 οπότε $R = d \rightarrow B'' = \dots$



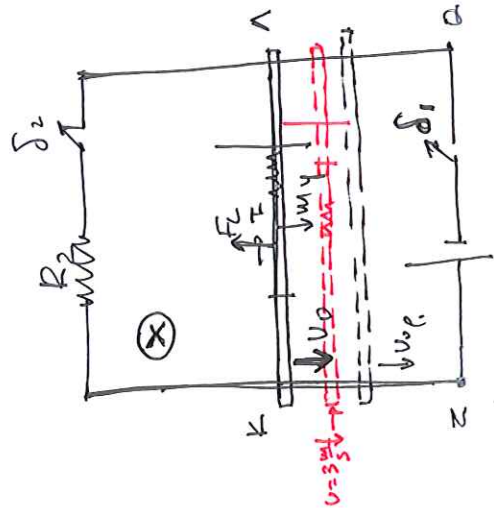
* Την στροφομή που έχει ΣΕΧΗΜΕΤΕ ΤΗΝ.

ΑΣΚ 61.



α) $\Sigma F = 0 \Rightarrow B \frac{E}{R_2} l = m \cdot g \quad (1)$

β)



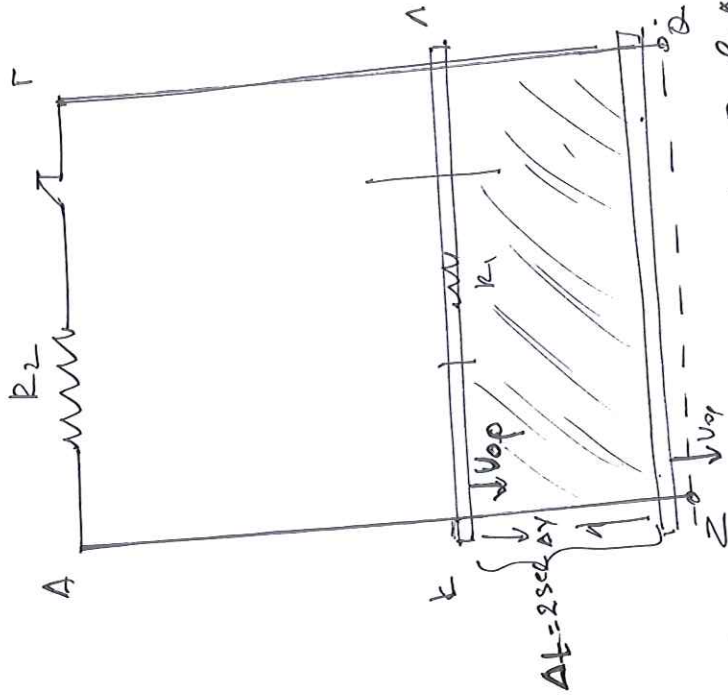
Την $t=0^+$ $\Sigma F = m \cdot g - B \left(\frac{B \cdot l \cdot \rho}{R_1 + R_2} \right) l < 0$.

ΑΡΑ ΘΑ ΚΑΝΕΙ ΓΙΒΡΑΔΥΝΟΜΕΝΗ ΚΙΝΗΣΗ
ΘΑ ΑΠΟΚΤΗΣΕΙ v_{op} ΟΤΑΝ

$\Sigma F = 0 \Rightarrow m \cdot g - \frac{B^2 v_{op}^2 l^2}{R_1 + R_2} = 0 \Rightarrow \dots v_{op} =$

γ) ΟΤΑΝ $v = 3 \text{ m/s}$

$\frac{\Delta \rho}{\Delta t} = \Sigma F = m \cdot g - B \frac{B \cdot l \cdot \rho}{R_1 + R_2} l$

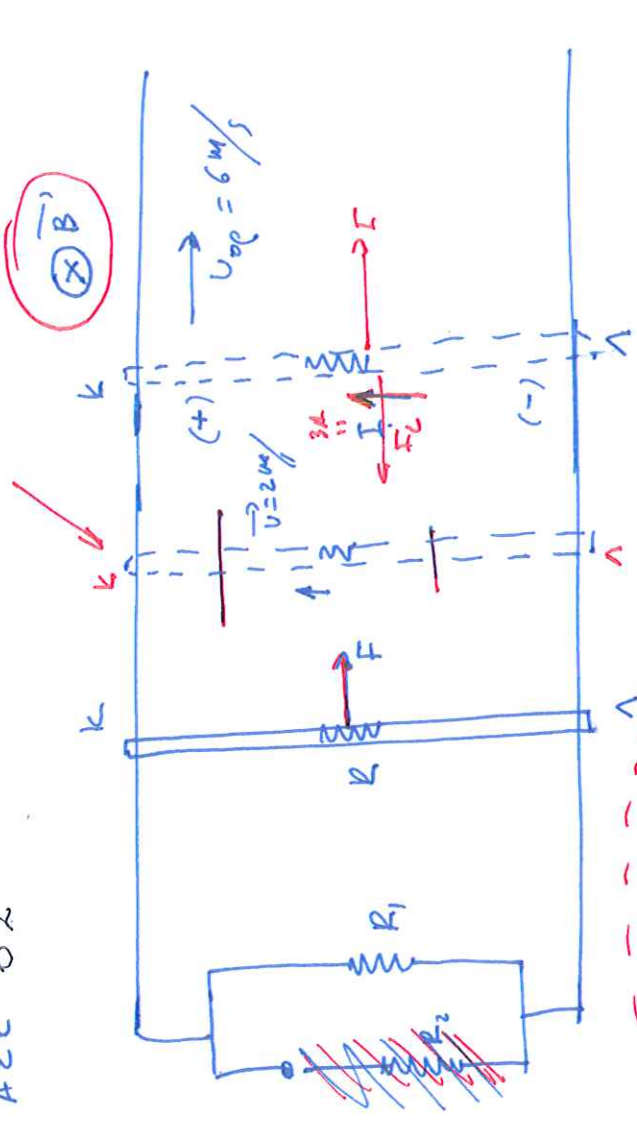


$\Delta \phi = B \cdot l \cdot \Delta y = B \cdot l \cdot v_{op} \cdot \Delta t$

$q = I \cdot \Delta t$

$Q = I^2 R_{ext} \Delta t$

$V_{KA} = \mathcal{E}_{\text{EM}} - i \cdot R_1$
 $V_{KN} = B \cdot l \cdot v_{op} - \frac{B \cdot l \cdot R_1}{R_1 + R_2}$



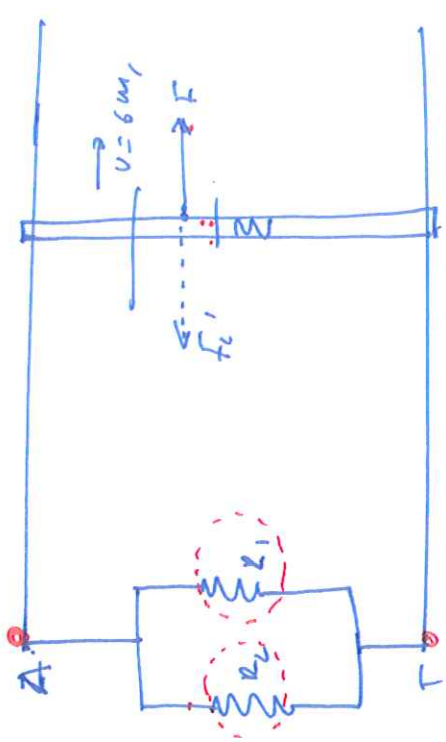
$W_f = kv + \mathcal{E} R_{eq}$
 $I = \frac{Bvl}{R_1 + R_2} = 0 \quad v_{op} = 6 \text{ m/s}$
 $F = B \cdot l \cdot I \Rightarrow B = 1 \text{ T}$

$V_{kq} = Bvl - I_1 R = 4 - 1 = 3 \text{ V}$

$I_1 = \frac{Bvl}{R_{eq}} = 1 \text{ A}$

$\frac{\Delta k}{\Delta t} = \Sigma F \cdot U = (F - F_c) \cdot U = (6 - 2) \cdot 2 = 8 \text{ J/s}$

$F_c = B \cdot I \cdot l = 2 \text{ N}$



$I' = \frac{Bvl}{R_{eq}} = \frac{12}{3} = 4 \text{ A}$

$\Sigma F = F - F_c = 6 \text{ N} - 8 \text{ N} = -2 \text{ N}$ (тільки сила ктриває)

- $P_{R_1} = I_1^2 R_1$ min ота $I_1, I_2 = \text{min}$
- $P_{R_2} = I_2^2 R_2$ ота ота $I_1 \rightarrow \text{min}$
- ота $U_{\text{отат}} I_2 \text{ ота } \Sigma F = 0$

$U \rightarrow U_{op} \text{ ота } \Sigma F = 0 \Rightarrow f = F_c' \Rightarrow$

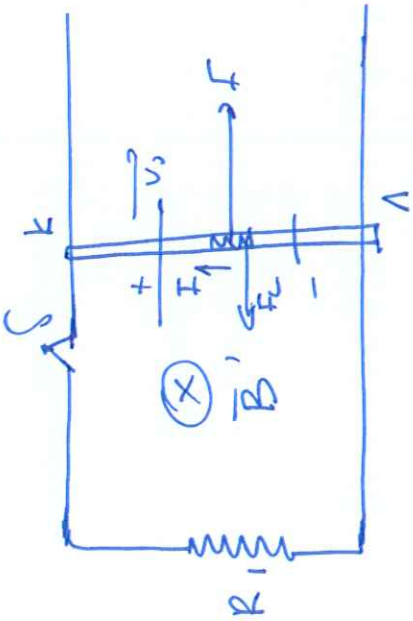
$\mathcal{E} = B \cdot I \cdot l \Rightarrow I = 3 \text{ A}$

$V_{\text{отат}} = I \cdot R_{1,2} = 6 \text{ V}$

$I_1 = \frac{V_{\text{отат}}}{R_1} = 2 \text{ A} \quad P_{R_1} = I_1^2 R_1 = 12 \text{ W}$

$I_2 = \frac{V_{\text{отат}}}{R_2} = 1 \text{ A} \quad P_{R_2} = I_2^2 R_2 = 6 \text{ W}$

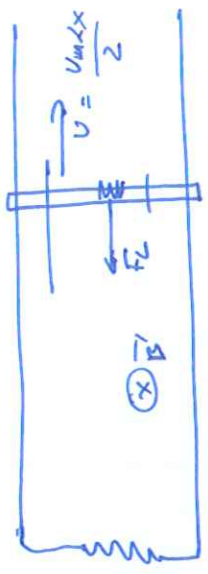
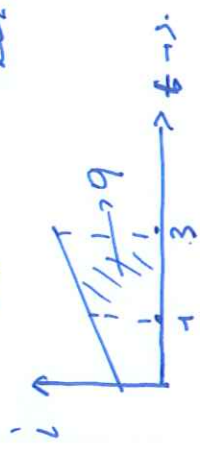
$P_{R_1, R_2} = 18 \text{ W}$



$l = 1 \text{ m}$
 $m = 0,5 \text{ kg}$
 $R_2 = 0,1 \Omega$
 $B = 1 \text{ T}$
 $v_0 = 2 \text{ m/s}$
 $\alpha = 1 \text{ m/s}^2$

$\alpha) \Sigma F = m \cdot a \Rightarrow F - F_L = m \cdot a$
 $\rightarrow F - B \cdot \frac{B v l}{R_{\text{eq}}} \cdot l = m \cdot a$
 $\Rightarrow F = \frac{B^2 l^2}{R_{\text{eq}}} (v_0 + \alpha t) + m \cdot a$

$\beta) i = \frac{\mathcal{E}_{\text{ind}}}{R_{\text{eq}}} = \frac{B \cdot l (v_0 + \alpha t)}{R_{\text{eq}}}$

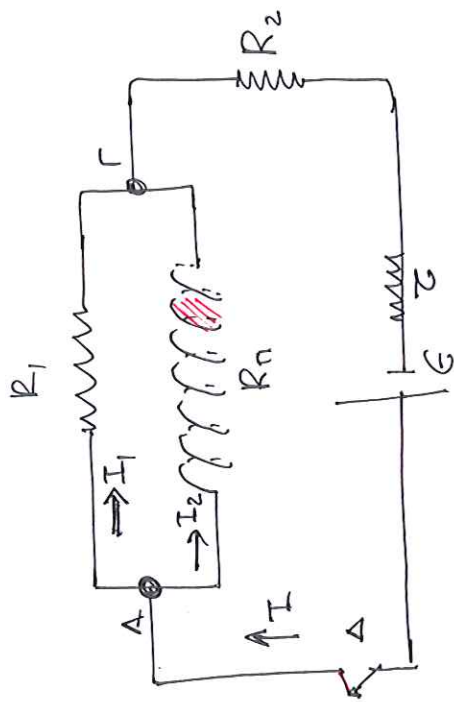


$v_{\text{max}} = v_{t=3\text{sec}} = v_0 + \alpha \cdot t = 2 + 1 \cdot 3 = 5 \text{ m/s}$
 $\text{ΟΤΑΝ } v = \frac{v_{\text{max}}}{2} = 2,5 \text{ m/s}$
 $\frac{\Delta p}{\Delta t} = \Sigma F = -F_L = -B \cdot I \cdot l = -B \frac{B v l}{R_{\text{eq}}} \cdot l$

$Q = \frac{1}{2} m v_{\text{max}}^2$

οδη η υναμικη ενεργεια του δυναμου
 εγινε διηλεκτικη ενταξη δε 716716μJ

ΑΣΚ 68



$$d) L = \mu_0 N^2 \left(\frac{\pi \delta^2}{l} \right)$$

$$6) I = \frac{E}{R_{on}}$$

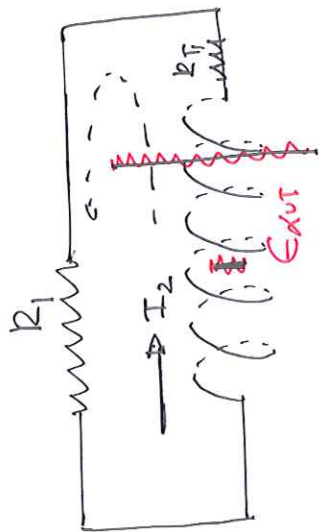
$$R_{on} = R_1 + R_2 + R_n$$

$$V_{AT} = I \cdot R_1 + R_n$$

$$I_1 = \frac{V_{AT}}{R_1}, \quad I_2 = \frac{V_{AT}}{R_n}$$

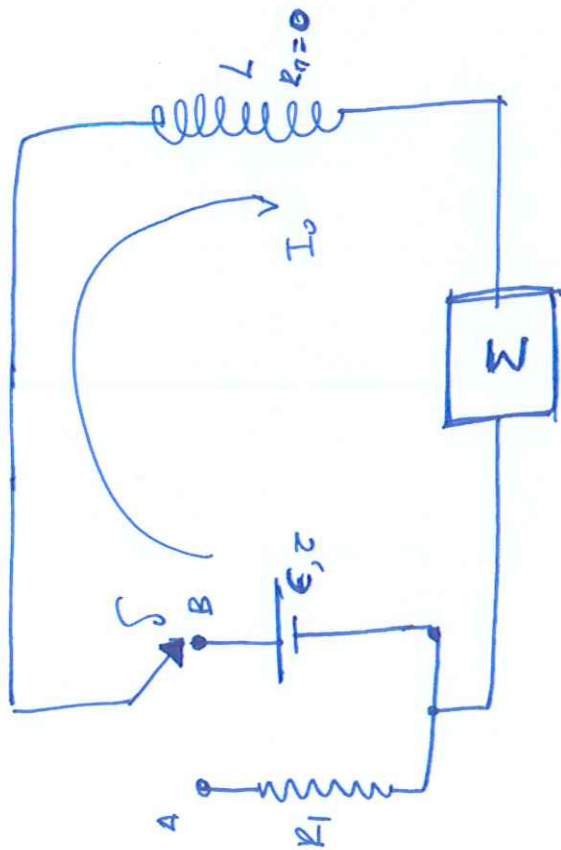
$$B_{\text{max}} = \mu_0 I_2 \frac{N}{l}$$

ΑΚΡΙΒΟΣ ΜΕΤΡ



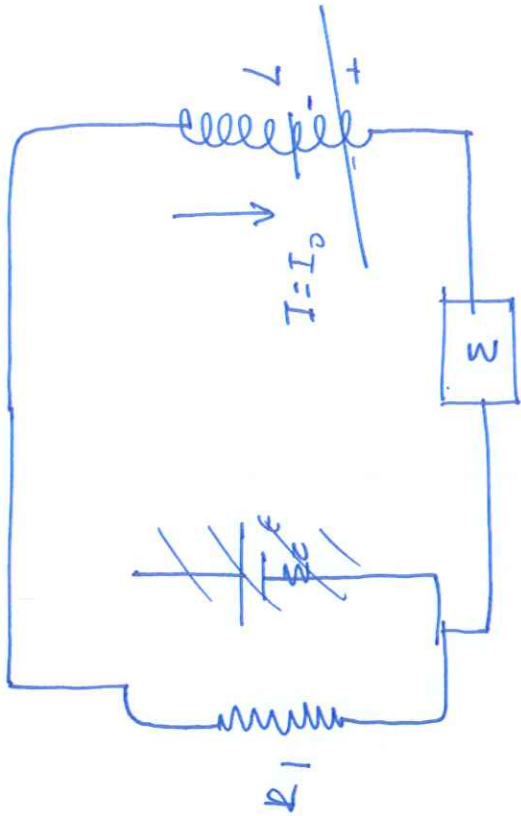
$$|E_{dut}| = L \left| \frac{\Delta I}{\Delta t} \right| \Rightarrow \frac{\Delta L}{\Delta t} = (-) \dots$$

$$\bullet Q_{onik_0} = U_L = \frac{1}{2} L I_2^2$$



a) $L = \mu_0 \frac{N^2}{l} A$

b) $I_2 = \frac{P_2}{V_2}$
 $I = \frac{\epsilon}{R_{on}} = \frac{\epsilon}{R_2 + Z}$



γ) $\dot{I} = \frac{\epsilon_{ind}}{R_{on}} = \frac{L \cdot \left| \frac{\Delta I'}{\Delta t} \right|}{R_1 + R_2} \Rightarrow$

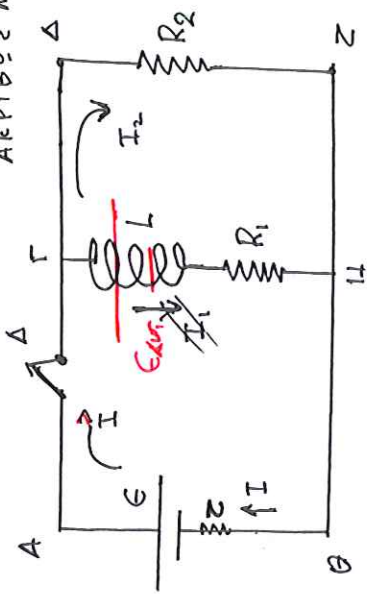
$\Rightarrow \frac{\Delta I'}{\Delta t} = (-) \dots$

δ) $Q_{on} = \frac{1}{2} L I_0^2$

$Q_{on} = Q_1 + Q_2 \left. \begin{array}{l} Q_1 = \dots \\ Q_2 = \dots \end{array} \right\}$
 $\frac{Q_1}{Q_2} = \frac{R_1}{R_2}$

ΑΣΚ 11

ΑΚΡΙΒΕΣ ΜΕΤΑ $\rightarrow I_1 = 0$



$I = I_2$

Ω² ΚΑΝΟΝΑ ΚΙΣΧΟΦ (Α Γ Δ Ζ Η Θ Α)

$-I_2 R_2 - I_2 \zeta + \epsilon = 0$

$\Rightarrow I = \frac{\epsilon}{R_2 + \zeta} = 2A$

$I_2 = I = 2A$

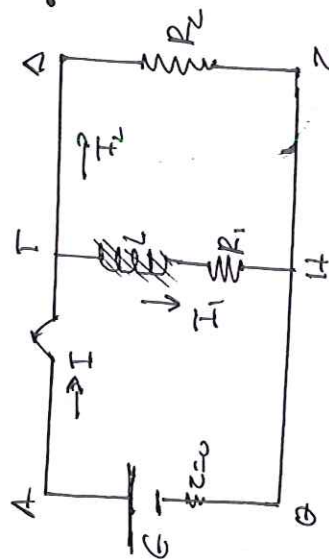
$E = 12V$

$\zeta = 0$

$R_1 = 3\Omega$

$R_2 = 6\Omega$

$L = 0,2H$



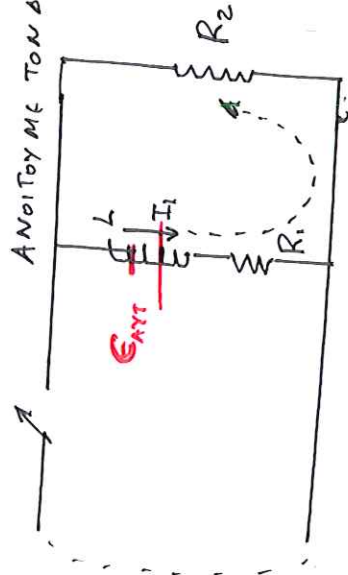
• ΟΤΑΝ ΤΑ ΡΕΥΜΑΤΑ ΓΙΝΑΙ ΣΤΑΘΕΡΑ

$\cdot I = \frac{\epsilon}{R_{1,2}} = 6A$

$I_1 = \frac{V_{\Gamma H}}{R_1} = \frac{\epsilon}{R_1} = 4A$

$I_2 = \frac{V_{\Delta Z}}{R_2} = \frac{\epsilon}{R_2} = 2A$

Ανοίγουμε τον διακόπτη

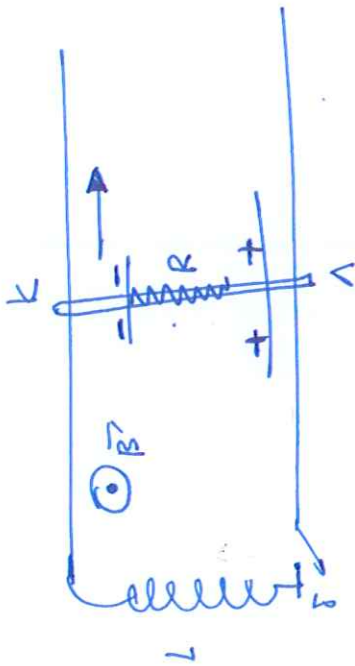


ΑΚΡΙΒΕΣ ΜΕΤΑ

Ι_{ΠΡΩΤΟ} = Ι₁ = 4 Α και μ₂ συννετχι
ΑΡΧ ΚΥΚΛΟΥΓΙΤΧΙ ΕΝΤ ΓΙΑ ΝΑ
ΤΟ ΒΩΤΥΡΥΘΜ.

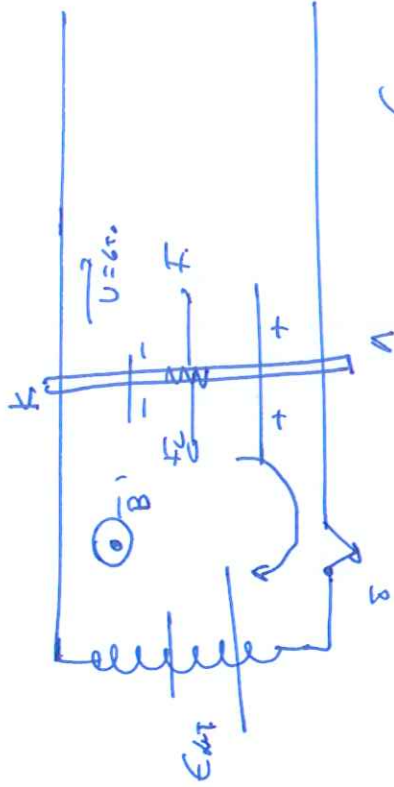
$\cdot Q = |\Delta U_L| = \left| U_L - \frac{1}{2} L I_1^2 \right|$

$Q = 1,6 J$



$l = 24$
 $l = 2 \text{ m}$
 $R = 4 \Omega$
 $U = 10 \text{ V/s}$
 $B = 1 \text{ T}$

1) $V_{KA} = \mathcal{E}_{\text{em}} = B \cdot U \cdot l$



2) $U_L^{\text{max}} = \frac{1}{2} L I_0^2$ ($I_0 = \frac{B U l}{R_{\text{tot}}}$)

οτις επισημασμενα Ι0 περικλ.

3) $i = \frac{B U l - \mathcal{E}_{\text{em}}}{R_{\text{tot}}}$

4) οτις $\frac{\Delta i}{\Delta t} = 4 \text{ A/s}$ $i = \frac{B U l - L \frac{\Delta i}{\Delta t}}{R_{\text{tot}}}$

και $F = F_L = B \cdot I \cdot l = \dots$